

GUJARAT TECHNOLOGICAL UNIVERSITY
BE - SEMESTER-VII (NEW) EXAMINATION – WINTER 2022

Subject Code:3171614**Date:12-01-2023****Subject Name:Computer Vision****Time:10:30 AM TO 01:00 PM****Total Marks:70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.
4. Simple and non-programmable scientific calculators are allowed.

		MARKS
Q.1	(a) Define the term: computer vision. Write difference(s) between image processing and computer vision.	03
	(b) How do we represent an image in computer? Explain in brief. Also list the various types of computer image?	04
	(c) Write and explain various applications of computer vision.	07
Q.2	(a) What is radiometry? Explain photometric image formation in detail.	03
	(b) Explain any two morphological operations in brief with neat sketches.	04
	(c) Write a detailed note on histogram equalization.	07
OR		
	(c) Explain image segmentation in brief. Also discuss various approaches for image segmentation.	07
Q.3	(a) What do you mean by image enhancement? What is need of the same?	03
	(b) Write the differences between rigid and affine transformation.	04
	(c) Elaborate the following image geometric operations with proper illustration: <ul style="list-style-type: none"> - Translation, - Rotation, - Scaling, and - Shearing. 	07
OR		
Q.3	(a) Write basic steps for filtering in the frequency domain.	03
	(b) Explain radial distortion in camera calibration.	04
	(c) Elaborate snake's method for active contours.	07
Q.4	(a) Discuss the concepts of motion parallax in brief.	03
	(b) What is descriptor? Explain SIFT descriptor in detail.	04
	(c) Explain intrinsic and extrinsic parameters related to camera models. Also state usefulness for these kinds of parameters in the field of computer vision.	07
OR		
Q.4	(a) Which approaches are for appearance based method in object recognition? Explain them in brief.	03
	(b) Explain Kalman filtering in motion tracking.	04
	(c) Write the need of corner detection. Elaborate any one method or algorithm for corner detection.	07
Q.5	(a) What is camera calibration? Explain pinhole camera models in detail.	03
	(b) What do you mean by noisy image? List various types of noise and explain each in brief.	04
	(c) Briefly explain edge detection. Explain any one method or algorithm for edge detection.	07

OR

- Q.5** (a) Write various applications of motion tracking. Explain each in brief. **03**
- (b) State differences between low pass filtering and high pass filtering. **04**
- (c) Write a detailed note on optical flow algorithm. **07**
