## **GUJARAT TECHNOLOGICAL UNIVERSITY** BE - SEMESTER–VII (NEW) EXAMINATION – WINTER 2021

Subject Code:3171614

Subject Name:Computer Vision

Time:10:30 AM TO 01:00 PM

## **Total Marks: 70**

Date:29/12/2021

Instructions:

- 1. Attempt all questions.
- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks.
- 4. Simple and non-programmable scientific calculators are allowed.

Q.1	(a)	What is Computer Vision? Enlist its applications and explain any two	MARKS 03
-		of them.	
	<b>(b</b> )	What is Radiometry? Explain photometric image formation in detail.	04
	( <b>c</b> )	What do you understand by geometric 2D transformation in image formation? Explain with examples.	07
Q.2	(a)	Define the terms: Image Digitization, Normalized cut and kernel.	03
	(b)	What is convolution? Explain the process of image convolution with example.	04
	( <b>c</b> )	Differentiate between low pass filtering and high pass filtering.	07
		OR	
	(c)	How do you perform filtering process in frequency domain? Show step by step process with clear diagram. Explain Butterworth Low Pass filter in frequency domain.	07
0.3	(a)	Discuss active contour technique for Segmentation.	03
C C	<b>(b)</b>	What is descriptor? Explain SIFT descriptor in detail.	04
	(c)	What is histogram? Explain histogram equalization algorithm. Write Matlab code for calculation of histogram and histogram equalization.	07
		OR	
Q.3	<b>(a)</b>	What is segmentation? Explain graph based segmentation in detail.	03
	<b>(b)</b>	Explain region splitting and region merging in image segmentation.	04
	(c)	Explain K-means and Gaussian Mixture Model in detail.	07
Q.4	<b>(a)</b>	What is watershed? Explain watershed segmentation.	03
	<b>(b</b> )	Explain Pixel transform and color transform of image with an example.	04
	(c)	What is Edge detection? Explain canny edge detection algorithm and write a MATLAB code to implement this algorithm.	07
		OR	

## Q.4(a) Explain shape context descriptors.03(b) Name two morphological operations and explain them with examples.04

	( <b>c</b> )	What is corner detection? Explain Moravec corner detection	07
		algorithm and write a MATLAB code to implement this algorithm.	
Q.5	<b>(a)</b>	Explain radial distortion in camera calibration.	03
	<b>(b</b> )	What is camera calibration? Explain pinhole camera models in detail.	04
	(c)	What is object recognition? Explain Different components of an object recognition system in detail.	07
		OR	
Q.5	<b>(a)</b>	Which approaches are for appearance based method in object recognition? Explain them in brief.	03
	<b>(b)</b>	Explain Kalman filtering in motion tracking.	04
	(c)	List the types of noise. Consider that image is corrupted by Gaussian noise. Suggest suitable method to minimize Gaussian noise from the image and explain that method.	07
		***	